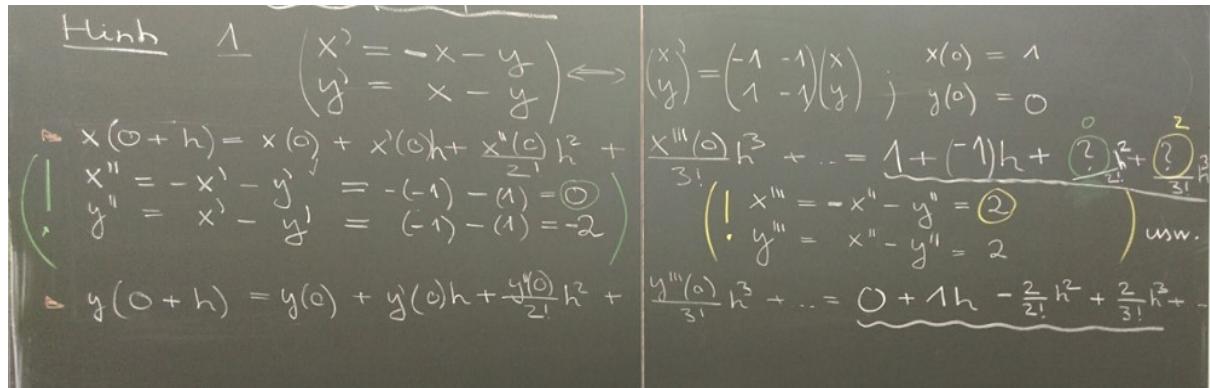


## Solutions 14: Numeric Ordinary Differential Equations IV

1. Solution from the classroom:



The image shows a handwritten derivation of a numerical method for a system of ordinary differential equations. It starts with the system  $\begin{cases} \dot{x} = -x - y \\ \dot{y} = x - y \end{cases}$  and the corresponding matrix form  $\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} -1 & -1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$ . Initial conditions are given as  $x(0) = 1$  and  $y(0) = 0$ . The derivation then proceeds to show the Taylor expansion up to the third order term, resulting in the formula  $y(0+h) = y(0) + y'(0)h + \frac{y''(0)}{2!}h^2 + \frac{y'''(0)}{3!}h^3 + \dots = 0 + 1h - \frac{2}{2!}h^2 + \frac{2}{3!}h^3$ .

2. Cf. P20.6 from Schaum's Outline of Numerical Analysis, Chapter 20.

Let  $x' = u$ ,  $y' = v$ ,  $z' = w$  be the velocity components. Then

$$u' = f_1(t, x, y, z, u, v, w) \quad v' = f_2(t, x, y, z, u, v, w) \quad w' = f_3(t, x, y, z, u, v, w)$$

These six equations are the required first-order system. Other systems of higher-order equations may be treated in the same way.

The dimension of the first-order ODE-system is 6.

3. Cf. P20.4 from Schaum's Outline of Numerical Analysis, Chapter 20.

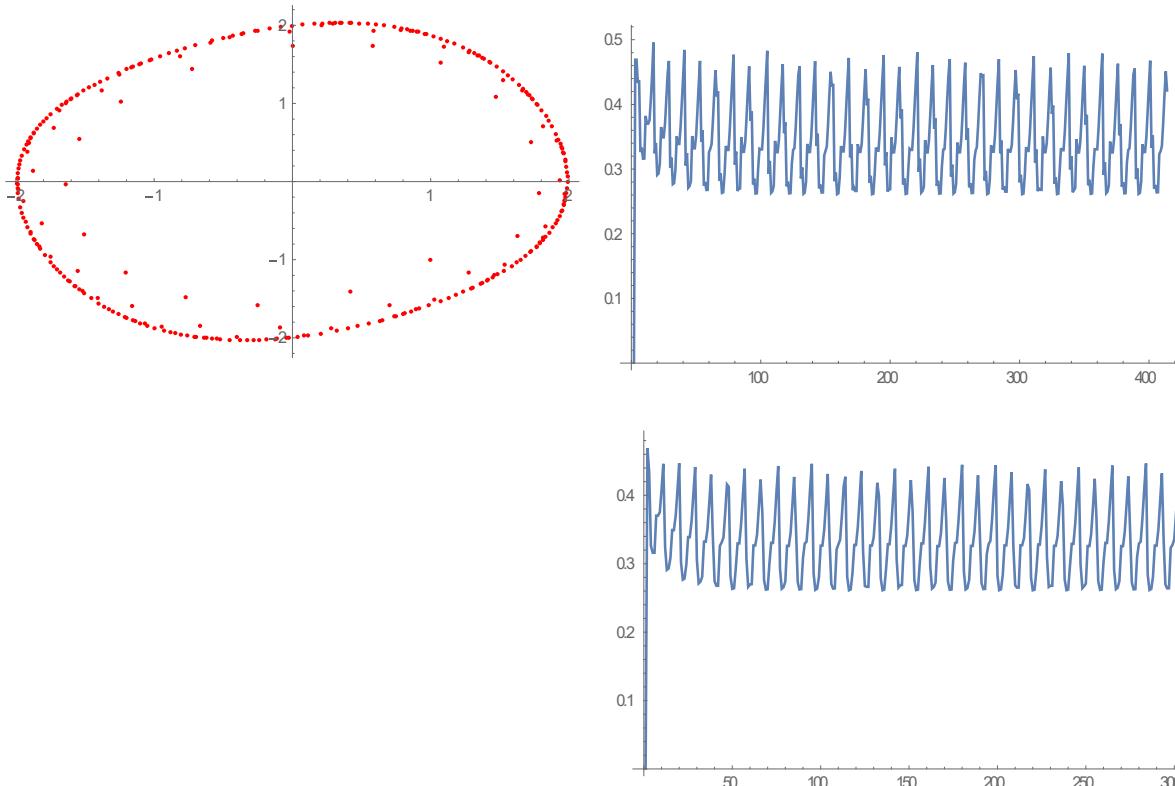
Let the second-order equation be  $y'' = f(x, y, y')$ . Then introducing  $p = y'$  we have at once  $y' = p$ ,  $p' = f(x, y, p)$ . As a result of this standard procedure a second-order equation may be treated by system methods if this seems desirable.

The initial conditions for the vector  $(p, y)$  are:  $p(x_0) = y_1$ ,  $y(x_0) = y_0$ .

4. From the script we know that the estimation of the error is equal to  $\vec{e}_k = \frac{1}{2} h_k (\vec{k}_2 - \vec{k}_1)$  and the step-size adaptation is ruled by the formula  $h_{new} = h_k \left\| \frac{\vec{e}_n}{\varepsilon_a + \varepsilon_r \vec{y}_n} \right\|^{-1/2}$  with  $\varepsilon_a = 10^{-1}$ ,  $\varepsilon_r = 10^{-2}$ .

x	y	h	e_k	$\left\  \frac{e_k}{\varepsilon_a + \varepsilon_r y_n} \right\ $	h_neu	Status	k1
0	( 1.000000000, -1.000000000 )	0.00100000000	( -5.000000000e-7, 2.999001000e-7 )	469.0415760	0.4690415760	Proceed	( -1.00, -1.00 )
0.00100000000	( 0.9989995000, -1.000999700 )	0.4690415760	( -0.1099339890, 0.06059334319 )	1.000254693	0.4691610377	Proceed	( -1.0, -0.99 )
0.4700415760	( 0.4195550341, -1.409166461 )	0.4691610377	( -0.07173212952, 0.1337985989 )	0.9234240375	0.4332345797	Reject	( -1.4, -0.65 )
0.4700415760	( 0.4195550341, -1.409166461 )	0.4332345797	( -0.06116684426, 0.1119369002 )	1.009579027	0.4373845456	Proceed	( -1.4, -0.65 )
0.9032761557	( -0.2521114495, -1.579602423 )	0.4373845456	( -0.004182800260, 0.2080474579 )	0.7460460194	0.3263089992	Reject	( -1, -0.04 )
0.9032761557	( -0.2521114495, -1.579602423 )	0.3263089992	( -0.002328082473, 0.1109948425 )	1.021398991	0.3332916827	Proceed	( -1, -0.04 )
1.229585155	( -0.7698780179, -1.482876770 )	0.3332916827	( 0.03605134912, 0.1277328531 )	0.9481434422	0.3160083232	Reject	( -1.48, 0.649 )

The next plots show the vector coordinates  $\{z, v\}$  of the solution evolving in time (100 sec) and the evolution of total (414) and proceeded (303) step-sizes.



5. Cf. P20.2 from Schaum's Outline of Numerical Analysis, Chapter 20.

$k_1 = hf_1(x_n, y_n, p_n)$	$k_3 = hf_1(x_n + \frac{1}{2}h, y_n + \frac{1}{2}k_2, p_n + \frac{1}{2}l_2)$
$l_1 = hf_2(x_n, y_n, p_n)$	$l_3 = hf_2(x_n + \frac{1}{2}h, y_n + \frac{1}{2}k_2, p_n + \frac{1}{2}l_2)$
$k_2 = hf_1(x_n + \frac{1}{2}h, y_n + \frac{1}{2}k_1, p_n + \frac{1}{2}l_1)$	$k_4 = hf_1(x_n + h, y_n + k_3, p_n + l_3)$
$l_2 = hf_2(x_n + \frac{1}{2}h, y_n + \frac{1}{2}k_1, p_n + \frac{1}{2}l_1)$	$l_4 = hf_2(x_n + h, y_n + k_3, p_n + l_3)$
$y_{n+1} = y_n + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)$	
$p_{n+1} = p_n + \frac{1}{6}(l_1 + 2l_2 + 2l_3 + l_4)$	

6. Cf. P20.7 from Schaum's Outline of Numerical Analysis, Chapter 20.

An equivalent first-order system is

$$\begin{aligned} y' &= p = f_1(t, y, p) \\ p' &= -y + (.1)(1 - y^2)p = f_2(t, y, p) \end{aligned}$$

The Runge-Kutta formulas for this system are

$$\begin{aligned} k_1 &= hp_n & l_1 &= h[-y_n + (.1)(1 - y_n^2)p_n] \\ k_2 &= h\left(p_n + \frac{1}{2}l_1\right) & l_2 &= h\left[-\left(y_n + \frac{1}{2}k_1\right) + (.1)\left[1 - \left(y_n + \frac{1}{2}k_1\right)^2\right]\left(p_n + \frac{1}{2}l_1\right)\right] \\ k_3 &= h\left(p_n + \frac{1}{2}l_2\right) & l_3 &= h\left\{-\left(y_n + \frac{1}{2}k_2\right) + (.1)\left[1 - \left(y_n + \frac{1}{2}k_2\right)^2\right]\left[p_n + \frac{1}{2}l_2\right]\right\} \\ k_4 &= h(p_n + l_3) & l_4 &= h\{-(y_n + k_3) + (.1)[1 - (y_n + k_3)^2](p_n + l_3)\} \end{aligned}$$

and

$$y_{n+1} = y_n + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4) \quad p_{n+1} = p_n + \frac{1}{6}(l_1 + 2l_2 + 2l_3 + l_4)$$

Choosing  $h = .2$ , computations produce the following results to three places:

$$\begin{aligned} k_1 &= (.2)(0) = 0 & l_1 &= (.2)[-1 + (.1)(1 - 1)(0)] = -.2 \\ k_2 &= (.2)(-.1) = -.02 & l_2 &= (.2)[-1 + (.1)(1 - 1)(-.1)] = -.2 \\ k_3 &= (.2)(-.1) = -.02 & l_3 &= (.2)[- .99 + (.1)(.02)(-.1)] \approx -.198 \\ k_4 &\approx (.2)(-.198) = -.04 & l_4 &= (.2)[-(.98) + (.1)(.04)(-.198)] \approx -.196 \end{aligned}$$

These values now combine into

$$y_1 = 1 + \frac{1}{6}(-.04 - .04 - .04) = .98$$

$$p_1 = 0 + \frac{1}{6}(-.2 - .4 - .396 - .196) \approx -.199$$