

### Exercises 14: Numeric Ordinary Differential Equations IV

The problems are solvable without a computer, normally. There are exceptions.

The symbol | means „or“, the symbol \* „optional“, the symbol \*\* „optional and advanced“ and the symbol © means that a computer is required or helpful.

1. Solve the 2d linear ODE-system below approximately by expanding Taylor series for  $x(t)$  and  $y(t)$  up to order 3:

$$\begin{aligned} x' &= -x - y \\ y' &= x - y \quad x(0) = 1, \quad y(0) = 0 \end{aligned}$$

Hints:  $x(t) \approx x(0) + x'(0)t + \frac{x''(0)}{2}t^2 + \frac{x'''(0)}{6}t^3$ , e.g. The derivatives are gained iteratively:

$$x'(0) = -x(0) - y(0) = -1 - 0 = -1, \text{ then}$$

$$x''(0) = -x'(0) - y'(0) = 1 - (x - y) = 1 - (1 - 0) = 0 \text{ a.s.o.}$$

2. The acceleration equations below describe the trajectory  $(x(t), y(t), z(t))$  in 3d space of a particle:

$$x'' = f_1(t, x, y, z, x', y', z')$$

$$y'' = f_2(t, x, y, z, x', y', z')$$

$$z'' = f_3(t, x, y, z, x', y', z')$$

Write down the equivalent ODE-system of 1st order. What is its dimension?

3. Transform the 2nd order scalar ODE  $y'' = f(x, y, y')$   $y(x_0) = y_0, y'(x_0) = y_1$  into a first-order ODE-system taking into account the initial conditions.

4. © Solve the van-der-Pol ODE-system  $\begin{pmatrix} z' = v \\ v' = \mu(1 - z^2)v - z \end{pmatrix}$   $z(0) = 1, v(0) = -1, \mu = 0.2$

numerically by applying the Heun-Euler 2(1) embedded adaptive method with classical step-size control until 3 proceeding steps are executed. The initial step-size equals 0.001, the accuracy goal (ag) 1 and the precision goal is 2.

Create a table listing values for  $(t, \{z, v\}, h, e_k, \left\| \frac{\vec{e}_n}{\varepsilon_a + \varepsilon_r \vec{y}_n} \right\|^{-1/\tilde{p}}, h_{new}, state)$  containing at least

three proceeding steps.

Hints: The problem refers to Example 2.4 (script p. 41ff). The order is  $\tilde{p} = 2$ . The expression

$$\left\| \frac{\vec{e}_n}{\varepsilon_a + \varepsilon_r \vec{y}_n} \right\|^{-1/\tilde{p}} \text{ is a short form for } \max \left\{ \frac{|\vec{e}_n^{(1)}|}{\varepsilon_a + \varepsilon_r |\vec{y}_n^{(1)}|}, \frac{|\vec{e}_n^{(2)}|}{\varepsilon_a + \varepsilon_r |\vec{y}_n^{(2)}|} \right\}^{-\frac{1}{\tilde{p}}}.$$

5. Write down the classical Runge-Kutta scheme for the 2d ODE-system

$$y' = f_1(x, y, p)$$

$$p' = f_2(x, y, p) \quad y(x_0) = y_0, \quad p(x_0) = p_0$$

6. © Carry out numerically the first step with the classical Runge-Kutta scheme for the 2nd order differential equation (van der Pol) with step-size  $h = 0.2$ :

$$y'' - 0.1(1 - y^2)y' + y = 0 \quad y(0) = 1, \quad y'(0) = 0$$